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(54) Abstract Title

Quick coupling device with over centre spring

(57) A quick coupling device for quickly and easily coupling and decoupling a work implement 12 to and from a stick assembly 14 is disclosed. The quick coupling device includes a hook member 18,20 defined in the stick assembly. The hook member defines a recess. An implement pin 26,28 secured to the work implement is positionable within the recess. The quick coupling device further includes an over-center spring 34,36 which biases or otherwise secures the implement pin within the recess. The quick coupling device yet further includes an actuator 52,54 which selectively loads the over-center spring so as to secure the implement pin within the recess, or alternatively removes the load from the over-center spring so as to allow the bucket to be decoupled from the stick assembly. In one embodiment, Fig 1 the actuator 52,54 includes a operator controlled fluid cylinder, whereas in another embodiment (Fig 3 and 4) the actuator includes a lever assembly having a lever (152,154) with a cam lobe secured thereto. In the later case, a tool (172, Fig 6) is used to release the over centre spring. In the former case, the actuator is preferably a single acting, hydraulic actuated, spring pressed actuator (Fig 5). Preferably the over centre spring has a load shoe 38, 40 on its end.

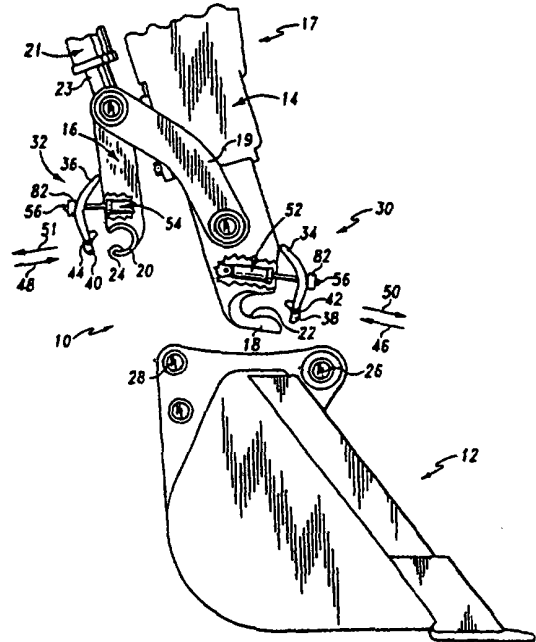


Fig. 1

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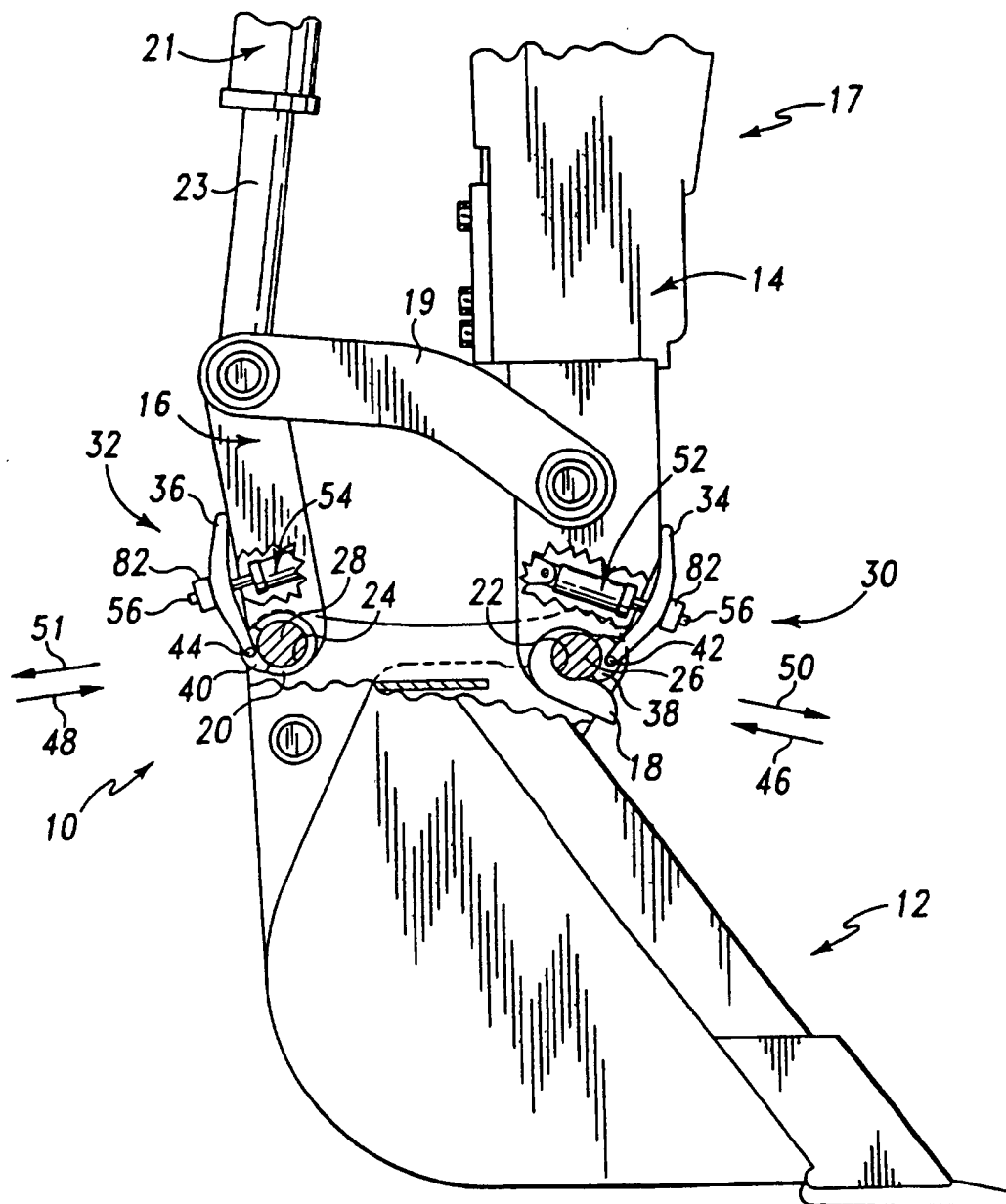


Fig. 2

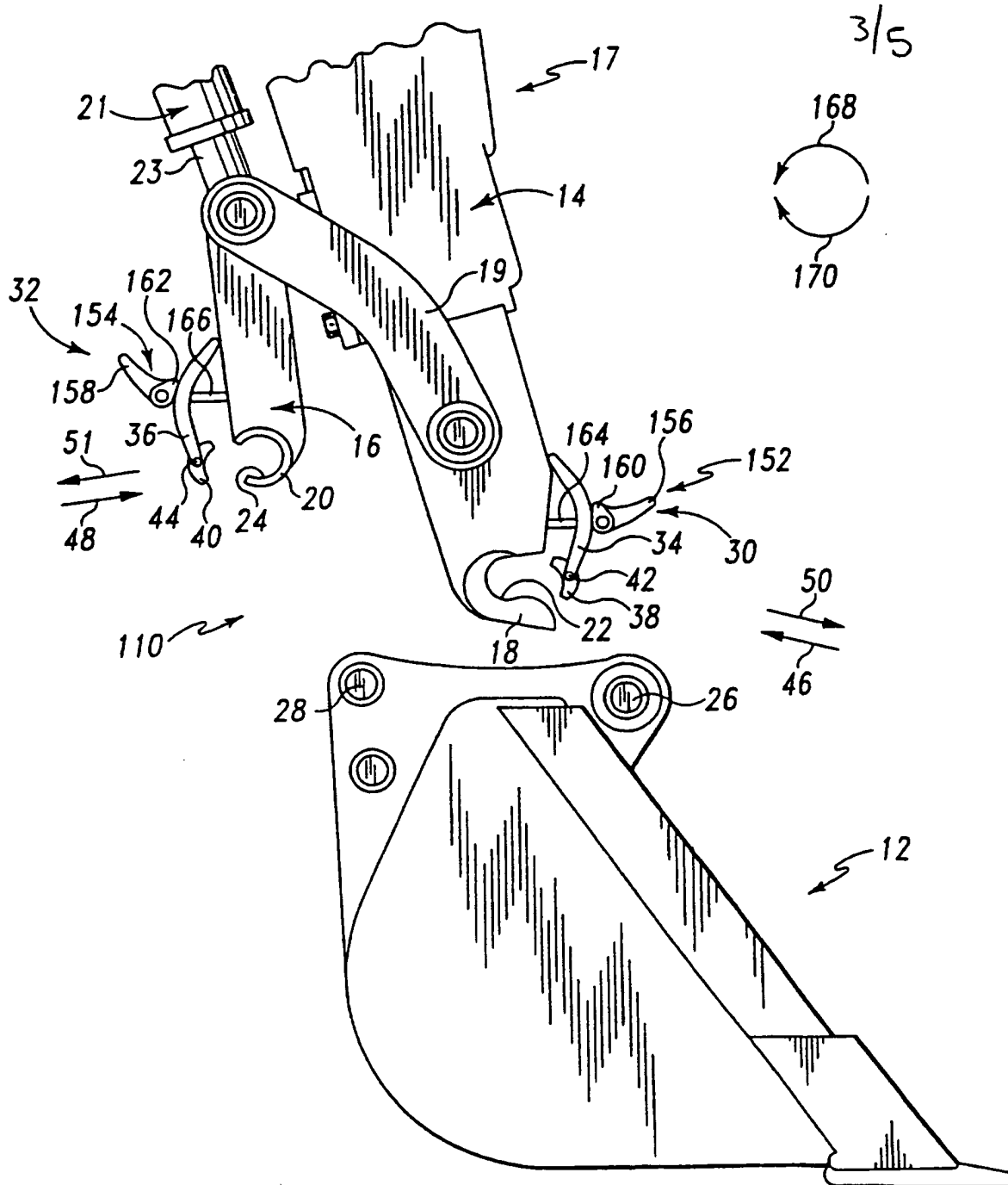


Fig. 3

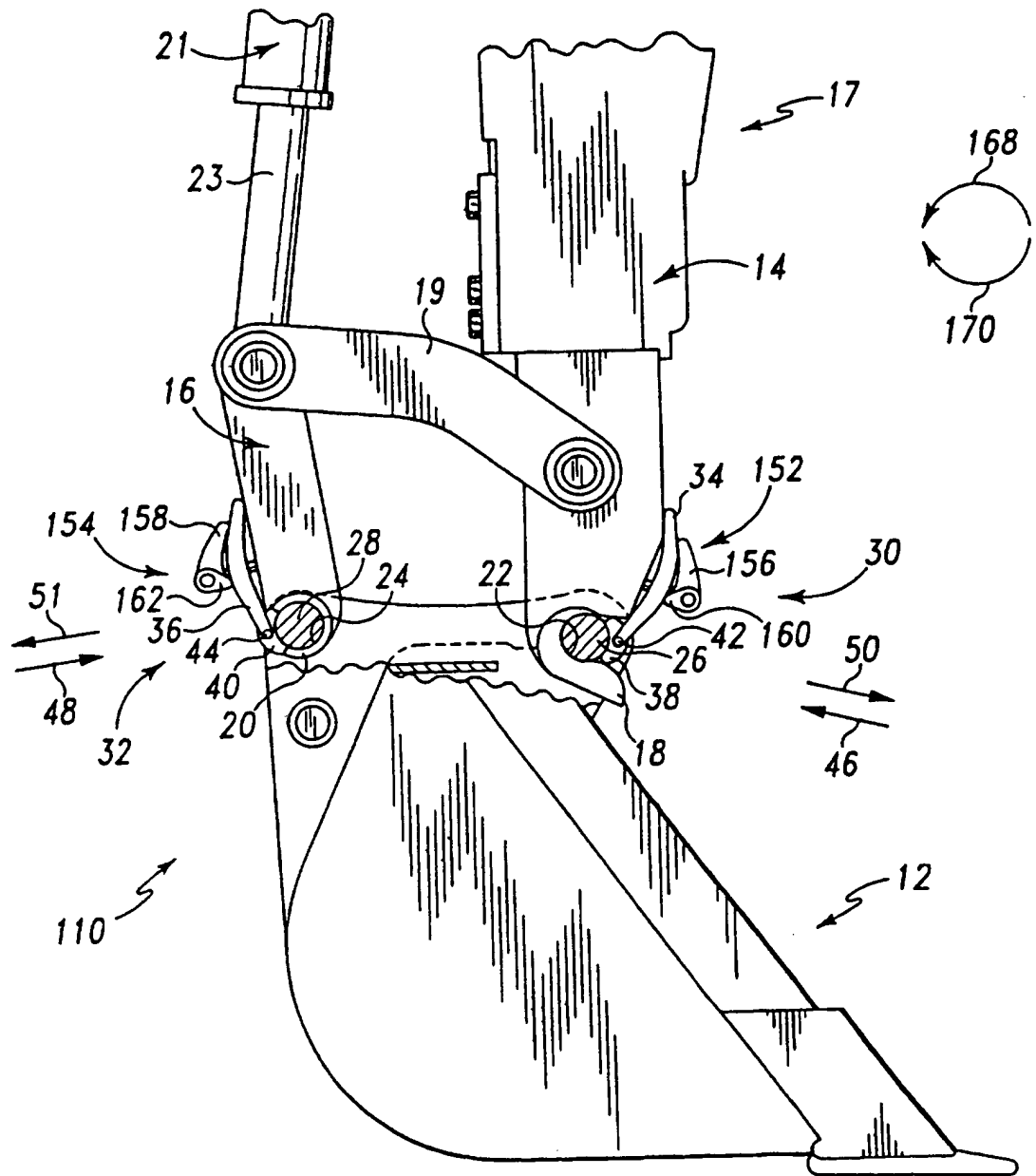


Fig. 4

Fig. 5

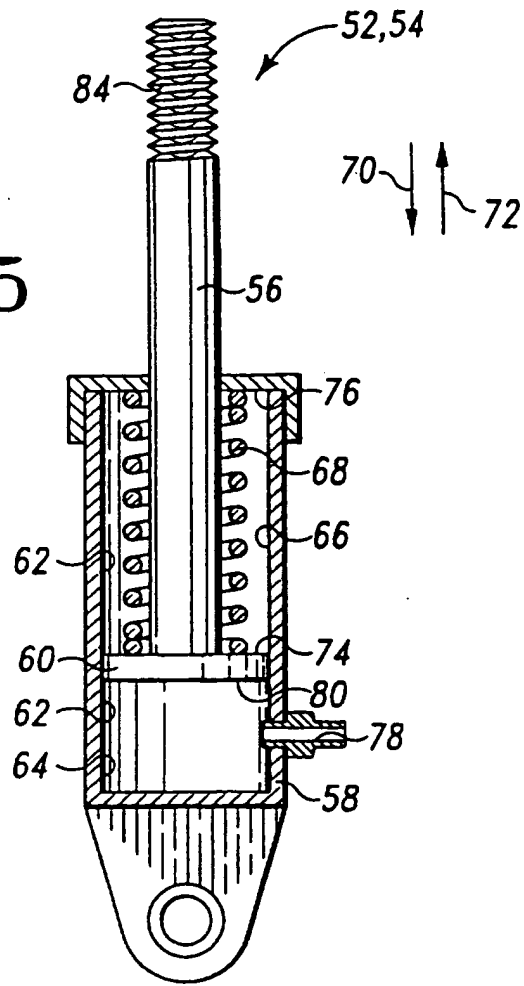
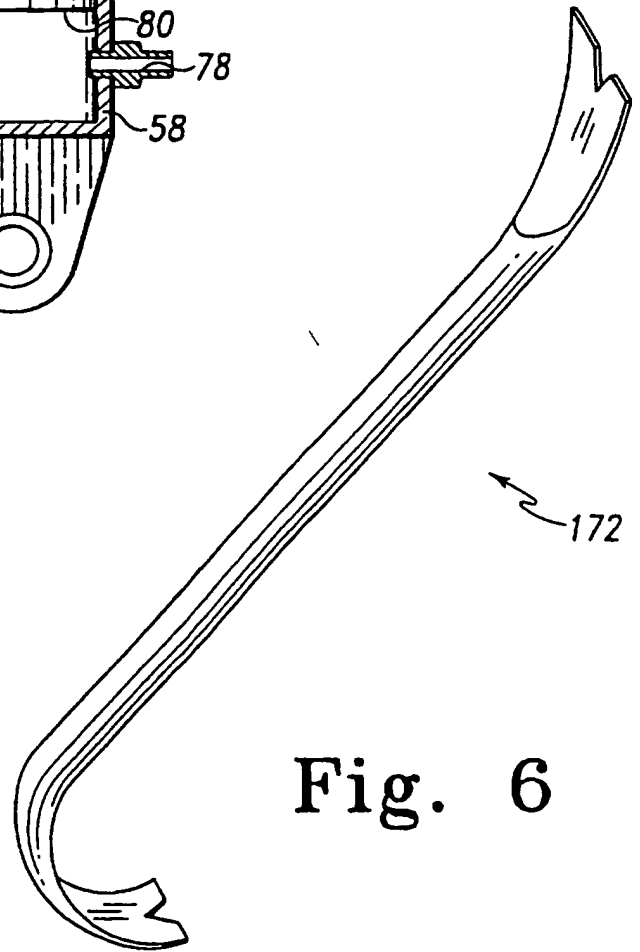


Fig. 6



QUICK COUPLING DEVICE AND METHOD  
UTILIZING AN OVER-CENTER SPRING

5

Technical Field of the Invention

The present invention relates generally to a work machine, and more particularly to a quick coupling device and method which provides quick and easy  
10 coupling of a work implement to a work machine.

Background of the Invention

Work machines, such as excavators and backhoes, are generally equipped with a digging and  
15 material handling bucket. In particular, the work machine typically includes a stick assembly which has the bucket attached thereto. The bucket is particularly useful for digging or otherwise excavating dirt or other types of material generally present at a  
20 work site.

However, during operation of the work machine, it is often desirable to exchange the bucket for a different work implement. In particular, many different types and sizes of buckets are available for  
25 attaching to the stick assembly of the work machine in order to facilitate performance of a given work operation. Hence, it may be necessary for a bucket of a first size to be removed from the stick assembly in order to be replaced by a bucket of a second size. In  
30 addition to digging buckets, many different types of work implements are also available for use by the work machine. For example, it may be desirable to couple a hydraulic hammer or a grapple to the work machine.

Disconnecting one work implement (e.g. a  
35 first digging bucket) and attaching a different work

implement (e.g. a second, larger digging bucket) is often a difficult and time consuming task. In particular, an operator of the work machine must leave the cab of the work machine, disconnect a number of pins, bolts, or other types of fasteners which are provided to mechanically couple the first bucket to the stick assembly. The operator must then mechanically couple the second bucket to the work machine by reconnecting the pins, bolts, and other fasteners associated with the second bucket to the stick assembly. It should be appreciated that during the period of time required to change or swap the buckets, the work machine is idle thereby disadvantageously decreasing the efficiency or productivity of the work machine.

In order to quickly mechanically couple and/or decouple work implements, a number of "quick coupling devices" have heretofore been designed. Such quick coupling devices typically include an apparatus which attempts to quickly and easily mechanically couple and/or decouple the work implement to and/or from the stick assembly. However, many of the quick coupling devices which have heretofore been designed are relatively mechanically complex, and have a relatively large number of components associated therewith thereby disadvantageously increasing costs associated with the work machine.

What is needed therefore is a quick coupling device which overcomes one or more of the aforementioned drawbacks. What is further needed is a quick coupling device which is less mechanically complex relative to quick coupling devices which have heretofore been designed.



Summary of the Disclosure

In accordance with a first embodiment of the present invention, there is provided an apparatus for coupling a work implement to a stick assembly. The apparatus includes a hook member defined in the stick assembly. The hook member defines a recess. The apparatus also includes an implement pin secured to the work implement. The implement pin is positionable between (1) a first pin position in which the implement pin is located within the recess, and (2) a second pin position in which the implement pin is spaced apart from the recess. The apparatus further includes an over-center spring which is positionable between (1) a first spring position in which the over-center spring biases the implement pin into the first pin position, and (2) a second spring position in which the over-center spring allows the implement pin to advance between the first pin position and the second pin position. The apparatus yet further includes an actuator which moves the over-center spring between the first spring position and the second spring position.

In accordance with a second embodiment of the present invention, there is provided an apparatus for coupling a work implement to a stick assembly, with the stick assembly having a structural arm and a tilt link. The apparatus includes a first hook member defined in the structural arm. The first hook member defining a first recess. The apparatus further includes a second hook member defined in the tilt link. The second hook member defining a second recess. The apparatus yet further includes a structural implement pin secured to the work implement, the structural pin being positionable between (1) a first structural pin position in which the structural pin is located within the first recess, and (2) a second structural pin

position in which the structural pin is spaced apart from the first recess. Moreover, the apparatus includes a tilt implement pin secured to the work implement, the tilt pin being positionable between (1) a first tilt pin position in which the tilt pin is located within the second recess, and (2) a second tilt pin position in which the tilt pin is spaced apart from the second recess. The apparatus also includes a structural over-center spring which is secured to the structural arm, the structural spring being positionable between (1) a first structural spring position in which the structural spring biases the structural pin into the first structural pin position, and (2) a second structural spring position in which the structural spring allows the structural pin to advance between the first structural pin position and the second structural pin position. The apparatus moreover includes a tilt over-center spring which is secured to the tilt link, the tilt spring being positionable between (1) a first tilt spring position in which the tilt spring biases the tilt pin into the first tilt pin position, and (2) a second tilt spring position in which the tilt spring allows the tilt pin to advance between the first tilt pin position and the second tilt pin position. The apparatus further includes a structural actuator which moves the structural spring between the first structural spring position and the second structural spring position. The apparatus moreover includes a tilt actuator which moves the tilt spring between the first tilt spring position and the second tilt spring position.

In accordance with a third embodiment of the present invention, there is provided a method for coupling a work implement to a stick assembly. The method includes the step of positioning an implement

pin which is secured to the work implement into a recess of a hook member defined in the stick assembly. The method also includes the step of advancing an actuator from a first actuator position to a second  
5 actuator position. The method further includes the step of moving an over-center spring from a unloaded position in which the over-center spring allows the implement pin to advance into the recess of the hook member to a loaded position in which the over-center  
10 spring biases the pin into the recess of the hook member, wherein the moving step occurs in response to the advancing step.

#### Brief Description of the Drawings

15 FIG. 1 is a fragmentary side elevational view of the bucket and the stick assembly of a work machine which shows a first embodiment of a quick coupling device which incorporates the features of the present invention therein;

20 FIG. 2 is a similar to FIG. 1, but showing the bucket coupled to the stick assembly of the work machine, with a portion of the bucket having been cut away for clarity of description;

FIG. 3 is a fragmentary side elevational view  
25 of the bucket and the stick assembly of a work machine which shows a second embodiment of a quick coupling device which incorporates the features of the present invention therein;

FIG. 4 is a view similar to FIG. 3, but  
30 showing the bucket coupled to the stick assembly of the work machine, with a portion of the bucket having been cut away for clarity of description;

FIG. 5 is a cross-sectional view of the fluid cylinder of the quick coupling device of FIG. 1; and

FIG. 6 is a perspective view of a tool bar which is used to lock and unlock the quick coupling device of FIG. 3.

5 Best Mode for Carrying Out the Invention

While the invention is susceptible to various modifications and alternative forms, specific embodiments thereof have been shown by way of example in the drawings and will herein be described in detail.

10 It should be understood, however, that there is no intent to limit the invention to the particular forms disclosed, but on the contrary, the intention is to cover all modifications, equivalents, and alternatives falling within the spirit and scope of the invention as  
15 defined by the appended claims.

Referring now to FIGS. 1 and 2, there is shown a quick coupling device 10 for coupling and decoupling a work implement 12, such as a digging bucket, to and from a structural arm 14 and a tilt link  
20 16 of a stick assembly 17 associated with a work machine (not shown) such as an excavator or backhoe. It should be appreciated that when the bucket 12 is secured to the structural arm 14 and the tilt link 16 with the quick coupling device 10, the bucket 12 may be  
25 used by the work machine to perform a work operation such as excavating. In particular, the stick assembly 17 further includes a guide link 19 which is pivotally coupled to both the structural arm 14 and the tilt link 16 thereby allowing the tilt link 16 to move relative  
30 to the structural arm 14. The motive power for such movement is provided by a tilt cylinder 21 having a rod 23 which may be selectively extended and retracted in order to alter the position of the tilt link 16 thereby facilitating movement of the bucket 12 during a work  
35 operation. Moreover, the tilt cylinder 21 may be used

to alter the position of the tilt link 16 in order to facilitate coupling and decoupling of the bucket 12 during an implement exchange procedure.

The quick coupling device 10 includes first  
5 hook member 18 defined in a first end of the structural arm 14, and a second hook member 20 defined in a first end of the tilt link 16. The first hook member 18 defines an outwardly opening recess 22, whereas the second hook member 20 defines an outwardly opening  
10 recess 24. As shown in FIG. 1, the recess 22 opens outwardly in a direction which is substantially opposite to the direction in which the recess 24 opens.

The bucket 12 has a first or structural  
implement pin 26 and a second or tilt implement pin 28  
15 secured thereto. As shall be discussed below in more detail below, when the first implement pin 26 is secured within the first hook member 18 and the second implement pin 28 is secured within the second hook member 20, the bucket 12 is secured to stick assembly  
20 17 thereby enabling use of the bucket 12 during a work operation such as excavating.

The quick coupling device 10 further includes a pair of clamping assemblies 30, 32. In particular, the clamping assembly 30 is secured to the structural  
25 arm 14, whereas the clamping assembly 32 is secured to the tilt link 16. The clamping assembly 30 includes a first or structural over-center load spring 34, whereas the clamping assembly 32 includes a second or tilt over-center load spring 36. The load springs 34, 36  
30 may be any type of bowed, over-center type leaf spring that when compressed beyond a predetermined point exerts a large load in a direction toward the recesses 22, 24, respectively.

A first end of each of the load springs 34,  
35 36 has a load shoe 38, 40, respectively, pivotally

secured thereto. In particular, the load shoes 38, 40 are coupled to the load springs 34, 36 via a pair of pin joints 42, 44, respectively. The load shoes 38, 40 are configured so as to be complementary to the shape of the outer surface of the implement pins 26, 28, respectively. Such a configuration enables the load shoes 38, 40 to evenly distribute the load generated by the load springs 34, 36 onto the implement pins 26, 28, respectively, when the implement pins 26, 28 are secured in the recesses 22, 24, respectively.

The load springs 34, 36 are positionable between a loaded position and an unloaded position. In particular, as shown in FIG. 2, once the load spring 34 has been urged or otherwise biased a predetermined distance in the general direction of arrow 46, the load spring 34 snaps into its loaded position in which the load spring 34 exerts a large load on the implement pin 26 through the load shoe 38. Similarly, as shown in FIG. 2, once the load spring 36 has been urged or otherwise biased a predetermined distance in the general direction of arrow 48, the load spring 36 snaps into its loaded position in which the load spring 36 exerts a large load on the implement pin 28 through the load shoe 40.

Conversely, as shown in FIG. 1, if the load spring 34 is urged or otherwise biased a predetermined distance in the general direction of arrow 50, the load spring 34 snaps into its unloaded position thereby removing the large load from the implement pin 26. Similarly, if the load spring 36 is urged or otherwise biased a predetermined distance in the general direction of arrow 51, the load spring 36 snaps into its unloaded position thereby removing the large load from the implement pin 28.

The orientation of the load springs 34, 36 is altered as the load springs 34, 36 are switched between their respective loaded positions and their respective unloaded positions. In particular, when the load  
5 springs 34, 36 are positioned in their respective unloaded positions, as shown in FIG. 1, the load springs 34, 36 assume a first bowed orientation, whereas when the load springs 34, 36 are positioned in their respective loaded positions, as shown in FIG. 2,  
10 the load springs 34, 36 assume a second bowed orientation. More specifically, as the load springs 34, 36 snap into their respective loaded positions, the load springs 34, 36 flatten out thereby assuming a shape or orientation which is substantially flatter  
15 (i.e. less bowed) relative to the shape or orientation of the load springs 34, 36 when positioned in their respective unloaded positions.

Moreover, it should be appreciated that the load springs 34, 36 maintain the same direction of  
20 concavity irrespective of whether the load springs 34, 36 are assuming the first bowed orientation (i.e. unloaded) or the second bowed orientation (i.e. loaded). What is meant herein by the phrase "same direction of concavity" is that the concave surface of  
25 the load springs 34, 36 face toward the structural arm 14 and the tilt link 16, respectively, irrespective of whether the load springs 34, 36 are positioned in their respective loaded positions or their respective unloaded positions. One type of load spring which is  
30 suitable for use as the load springs 34, 36 of the present invention, with minor modification thereof, is the over-center spring of the Universal Strap Clamp which is commercially available from Manhattan Supply Corporation of New York, New York as model number  
35 08104127.

In order to selectively switch the load springs 34, 36 between their respective loaded and unloaded positions, the clamping assemblies 30, 32 each include an actuator or fluid cylinder 52, 54. In particular, a first or structural fluid cylinder 52 is secured to the structural arm 14, whereas a second or tilt fluid cylinder 54 is secured to the tilt link 16.

The fluid cylinders 52, 54 are preferably operator controlled fluid cylinders each having a rod 56 extending from a housing 58, as shown in FIG. 5. The rod 56 is coupled at a first end to a piston 60 which translates within a cylinder chamber 62 defined in the housing 58. The piston 60 divides the cylinder chamber 62 thereby defining a fluid chamber 64 and a spring chamber 66. A cylinder spring 68 is disposed in the spring chamber 66 in order to urge or otherwise bias the rod 56 in the general direction of arrow 70 of FIG. 5 thereby placing the fluid cylinders 52, 54 in a respective first or rod retracted position. In particular, the cylinder spring 68 is disposed between an upper surface 74 of the piston 60 and an inner surface 76 of the housing 58 thereby creating a spring bias which urges the piston 60 and hence the rod 56 in the general direction of arrow 70.

Fluid pressure within the fluid chamber 64 selectively urges the rod 56 in the general direction of arrow 72. In particular, a fluid port 78 extends through the housing 58, and is coupled to an operator controlled fluid power circuit (not shown). When operation fluid is advanced under pressure into the fluid chamber 64, fluid pressure acts upon a lower surface 80 of the piston 60 thereby urging the piston 60 and hence the rod 56 in the general direction of arrow 72. It should be appreciated that when fluid pressure within the fluid chamber 64 is greater in



magnitude than the magnitude of the spring bias generated by the cylinder spring 68, the piston 60 and hence the rod 56 are moved in the general direction of arrow 72 thereby positioning the fluid cylinders 52, 54 in a respective second or rod extended position.

The fluid cylinders 52, 54 are secured to the load springs 34, 36. In particular, each of the load springs 34, 36 includes a saddle member 82. A threaded portion 84 of the rod 56 is secured to the saddle member 82 thereby coupling the fluid cylinders 52, 54 to the load springs 34, 36, respectively. Hence, the fluid cylinders 52, 54 may be used to selectively position the load springs 34, 36 in either their respective loaded positions or their respective unloaded positions. In particular, the magnitude of the spring bias generated by the cylinder springs 68 of the fluid cylinders 52, 56 is large enough that it causes the rods 56 to urge the load springs 34, 36 beyond a predetermined distance thereby causing the load springs 34, 36 to snap into their respective loaded positions.

Conversely, when high fluid pressure is present in the fluid chambers 64 of the fluid cylinders 52, 54 the rods 56 urge the load springs 34, 36 beyond a predetermined distance thereby causing the load springs to snap back into their respective unloaded positions. Hence, from the above discussion, it should be appreciated that the fluid cylinders 52, 54 may be used to position the load springs 34, 36 in their respective unloaded positions during an implement change procedure, as shown in FIG. 1. Thereafter, the fluid cylinders 52, 54 may be used to position the load springs 34, 36 in their respective loaded positions so as to secure the implement pins 26, 28 within the hook members 18, 20, respectively, once the implement pins

26, 28 have been received into the recesses 22, 24, as shown in FIG. 2.

Referring now to FIGS. 3-4, there is shown a quick coupling device 110 which is a second embodiment of the present invention. The quick coupling device 110 is somewhat similar to quick coupling device 10. Thus, the same reference numerals are used in FIGS. 3-4 to designate common components which were previously discussed in regard to FIGS. 1-2.

10 In lieu of the fluid cylinders 52, 54, the clamping assemblies 30, 32 of the quick coupling device 110 includes a pair of actuators or lever assemblies 152, 154. Each of the lever assemblies 152, 154 includes a lever 156, 158 having a cam lobe 160, 162, respectively, secured thereto. The levers 156, 158 rotate about a pair of pivot shafts such as bolts 164, 166, respectively, which are secured to the structural arm 14 and the tilt link 16, respectively.

The lever assemblies 152, 154 may be used to selectively position the load springs 34, 36 in either their respective loaded positions or their respective unloaded positions. In particular, rotation of the levers 156, 158 causes rotation of the cam lobes 160, 162, respectively, thereby exerting a bias or load on the load springs 34, 36, respectively. In particular, as the cam lobe 160 is rotated in the general direction of arrow 168, the load spring 34 is urged in the general direction of arrow 46. Rotation of the cam lobe 160 beyond the maximum height thereof causes the lever assembly 152 to assume a locked position thereby causing the load spring 34 to be urged beyond a predetermined distance which causes the load spring 34 to snap into its loaded position, as shown in FIG. 4. Similarly, as the cam lobe 162 is rotated in the general direction of arrow 170, the load spring 36 is

urged in the general direction of arrow 48. Rotation of the cam lobe 162 beyond the maximum height thereof causes the lever assembly 154 to assume a locked position thereby causing the load spring 36 to be urged  
5 beyond a predetermined distance which causes the load spring 36 to snap into its loaded position, as shown in FIG. 4.

Conversely, rotation of the levers 156, 158 in the opposite direction causes the bias or load  
10 exerted on the load springs 34, 36, respectively, by the cam lobes 160, 162, respectively, to be removed therefrom. In particular, rotation of the cam lobe 160 in the general direction of arrow 170 beyond the maximum height thereof, positions the lever assembly  
15 152 in an unlocked position thereby removing the load generated by the cam lobe 160 from the load spring 34 which allows the load spring 34 to snap back into its unloaded position, as shown in FIG. 3. Similarly, rotation of the cam lobe 162 in the general direction  
20 of arrow 168 beyond the maximum height thereof, positions the lever assembly 154 in an unlocked position thereby removing the load generated by the cam lobe 162 from the load spring 36 which allows the load spring 36 to snap back into its unloaded position, as  
25 shown in FIG. 3

It should be appreciated that the cam lobes 160, 162 generate a relatively high load (e.g. 2000 pounds) on the load springs 34, 36 in order to get the load springs 34, 36 to snap into their respective  
30 loaded positions or their respective unloaded positions. Hence, it may be necessary for the operator of the work machine to utilize a tool 172 (see FIG. 6), such as a pole or crow bar, to gain the mechanical advantage necessary to rotate the levers 156, 158.

### Industrial Applicability

In operation, the quick coupling devices 10, 110 may be used to quickly and easily couple the stick assembly 17 to the bucket 12. In particular to  
5 operation of the quick coupling device 10, the stick assembly 17 is first lowered in a direction toward the bucket 12, as shown in FIG. 1, with the fluid cylinders 52, 54 positioned in their respective rod extended positions so as to position the load springs 34, 36 in  
10 their respective unloaded positions. The stick assembly 17 is then advanced such that the implement pins 26, 28 are received into the recesses 22, 24 of the hook members 18, 20, respectively. It should be appreciated that during such advancement, the tilt  
15 cylinder 21 may be used to alter the position of the tilt link 16 relative the structural arm 14 in order to facilitate alignment of the implement pins 26, 28 relative to the recesses 22, 24, respectively. Once the implement pins 26, 28 are positioned within the  
20 recesses 22, 24, respectively, the fluid cylinders 52, 54 are operated such that the fluid cylinders 52, 54 assume their respective rod retracted positions thereby causing the load springs 34, 36 to snap into their respective loaded positions as shown in FIG. 2. It  
25 should be appreciated that when the implement pins 26, 28 are positioned in the recesses 22, 24, respectively, and the load springs 34, 36 are positioned in their respective loaded positions, the bucket 12 is secured to the stick assembly 17 and may thereafter be used to  
30 perform a work operation such as excavating.

In order to decouple the bucket 12 from the stick assembly 17, high fluid pressure is generated in the fluid chamber 64 of the fluid cylinders 52, 54 (see FIG. 5) thereby causing the fluid cylinders 52, 54 to  
35 assume the rod extended position. As discussed above,

when the fluid cylinders 52, 54 are positioned in their respective rod extended positions, the load springs 34, 36 are snapped into their respective unloaded positions. Once the load springs 34, 36 are positioned in their respective unloaded positions, the stick assembly 17 may be moved such that the hook members 18, 20 are spaced apart from the implement pins 26, 28 thereby allowing the stick assembly 17 to be lifted away from the bucket 12.

10           In particular to operation of the quick coupling device 110, the stick assembly 17 is first lowered in a direction toward the bucket 12, as shown in FIG. 3, with the lever assemblies 152, 154 positioned in their respective unlocked positions so as to position the load springs 34, 36 in their respective unloaded positions. The stick assembly 17 is then advanced such that the implement pins 26, 28 are received into the recesses 22, 24 of the hook members 18, 20, respectively. It should be appreciated that during such advancement, the tilt cylinder 21 may be used to alter the position of the tilt link 16 relative to the structural arm 14 in order to facilitate alignment of the implement pins 26, 28 relative to the recesses 22, 24, respectively. Once the implement pins 26, 28 are positioned within the recesses 22, 24, respectively, the operator of the work machine may rotate the lever assemblies 152, 154 such that the lever assemblies 152, 154 are positioned in their respective locked positions thereby causing the load springs 34, 36 to snap into their respective loaded positions, as shown in FIG. 4. It should be appreciated that when the implement pins 26, 28 are positioned in the recesses 22, 24, respectively, and the load springs 34, 36 are positioned in their respective loaded positions, the bucket 12 is secured

to the stick assembly 17 and may thereafter be used to perform a work operation such as excavating.

In order to decouple the bucket 12 from the stick assembly 17, the lever assemblies 152, 154 are  
5 rotated in an opposite direction thereby causing the lever assemblies 152, 154 to assume their respective unlocked positions. As discussed above, when the lever assemblies 152, 154 are positioned in their respective unlocked positions, the load springs 34, 36 are snapped  
10 into their respective unloaded positions. Once the load springs 34, 36 are positioned in their respective unloaded positions, the stick assembly 17 may be moved such that the hook members 18, 20 are spaced apart from the implement pins 26, 28 thereby allowing the stick  
15 assembly 17 to be lifted away from the bucket 12.

While the invention has been illustrated and described in detail in the drawings and foregoing description, such illustration and description is to be considered as exemplary and not restrictive in  
20 character, it being understood that only the preferred embodiments have been shown and described and that all changes and modifications that come within the spirit of the invention are desired to be protected.

Further, it should be appreciated that  
25 although the work implement 12 is herein described as a digging bucket, the quick coupling devices 10, 110 may be used to couple and/or decouple the stick assembly 17 to and from other types of work implements. For example, the quick coupling devices 10, 110 may be used  
30 to couple and/or decouple a grapple or a hydraulic hammer to the stick assembly 17.

Claims

What is claimed is:

1. An apparatus for coupling a work  
5 implement to a stick assembly, comprising:  
a hook member defined in said stick assembly,  
said hook member defining a recess;  
an implement pin secured to said work  
implement, said implement pin being positionable  
10 between (1) a first pin position in which said  
implement pin is located within said recess, and (2) a  
second pin position in which said implement pin is  
spaced apart from said recess;  
an over-center spring which is positionable  
15 between (1) a first spring position in which said over-  
center spring biases said implement pin into said first  
pin position, and (2) a second spring position in which  
said over-center spring allows said implement pin to  
advance between said first pin position and said second  
20 pin position; and  
an actuator which moves said over-center  
spring between said first spring position and said  
second spring position.
- 25 2. The apparatus of claim 1, further  
comprising a load shoe pivotally coupled to said over-  
center spring, wherein:  
said load shoe contacts said implement pin  
when said over-center spring is positioned in said  
30 first spring position, and  
said load shoe is spaced apart from said  
implement pin when said over-center spring is  
positioned in said second spring position.

3. The apparatus of claim 2, wherein said load shoe possesses a concave surface which is complementary to an outer surface of said implement pin.

5

4. The apparatus of claim 1, wherein:  
said over-center spring has a first bowed orientation and a second bowed orientation,  
said over-center spring assumes said first bowed orientation when said over-center spring is positioned in said first spring position,  
said over-center spring assumes said second bowed orientation when said over-center spring is positioned in said second spring position, and  
said first bowed orientation and said second bowed orientation each have the same direction of concavity.

5. The apparatus of claim 1, wherein:  
said actuator includes a fluid cylinder,  
said fluid cylinder is positionable between a first cylinder position and a second cylinder position,  
said fluid cylinder positions said over-center spring in said first spring position when said fluid cylinder is positioned in said first cylinder position, and  
said fluid cylinder positions said over-center spring in said second spring position when said fluid cylinder is positioned in said second cylinder position.



6. The apparatus of claim 5, wherein:  
said fluid cylinder includes a rod and a  
housing,

5       said rod is advanced so as to be retracted  
into said housing when said fluid cylinder is moved  
from said second cylinder position to said first  
cylinder position, and

      said rod is advanced so as to be extended out  
of said housing when said fluid cylinder is moved from  
10   said first cylinder position to said second cylinder  
position.

7. The apparatus of claim 6, wherein:  
      said fluid cylinder further includes a  
15   cylinder spring and a fluid chamber,  
      said cylinder spring urges said rod into said  
housing so as to position said fluid cylinder in said  
first cylinder position, and

      fluid pressure within said fluid chamber  
20   urges said rod out of said housing so as to position  
said fluid cylinder in said second cylinder position.

8. The apparatus of claim 1, wherein:  
      said actuator includes a lever positionable  
25   between a first lever position and a second lever  
position,  
      said lever positions said over-center spring  
in said first spring position when said lever is  
positioned in said first lever position, and  
30       said lever positions said over-center spring  
in said second spring position when said lever is  
positioned in said second lever position.

9. The apparatus of claim 8, wherein:  
said lever has a cam lobe secured thereto,  
and

rotation of said lever causes said cam lobe  
5 to move said over-center spring between said first  
spring position and said second spring position.

10. An apparatus for coupling a work  
implement to a stick assembly, with said stick assembly  
10 having a structural arm and a tilt link, comprising:  
a first hook member defined in said  
structural arm, said first hook member defining a first  
recess;

a second hook member defined in said tilt  
15 link, said second hook member defining a second recess;

a structural implement pin secured to said  
work implement, said structural pin being positionable  
between (1) a first structural pin position in which  
said structural pin is located within said first  
20 recess, and (2) a second structural pin position in  
which said structural pin is spaced apart from said  
first recess;

a tilt implement pin secured to said work  
implement, said tilt pin being positionable between (1)  
25 a first tilt pin position in which said tilt pin is  
located within said second recess, and (2) a second  
tilt pin position in which said tilt pin is spaced  
apart from said second recess;

a structural over-center spring which is  
30 secured to said structural arm, said structural spring  
being positionable between (1) a first structural  
spring position in which said structural spring biases  
said structural pin into said first structural pin  
position, and (2) a second structural spring position  
35 in which said structural spring allows said structural

pin to advance between said first structural pin position and said second structural pin position;

a tilt over-center spring which is secured to said tilt link, said tilt spring being positionable  
5 between (1) a first tilt spring position in which said tilt spring biases said tilt pin into said first tilt pin position, and (2) a second tilt spring position in which said tilt spring allows said tilt pin to advance between said first tilt pin position and said second  
10 tilt pin position;

a structural actuator which moves said structural spring between said first structural spring position and said second structural spring position; and

15 a tilt actuator which moves said tilt spring between said first tilt spring position and said second tilt spring position.

11. The apparatus of claim 10, further  
20 comprising:

a structural load shoe pivotally coupled to said structural spring,

a tilt load shoe pivotally coupled to said tilt spring,

25 wherein (1) said structural load shoe contacts said structural pin when said structural spring is positioned in said first structural spring position, (2) said structural load shoe is spaced apart from said structural pin when said structural spring is  
30 positioned in said second structural spring position, (3) said tilt load shoe contacts said tilt pin when said tilt spring is positioned in said first tilt spring position, and (4) said tilt load shoe is spaced apart from said tilt pin when said tilt spring is  
35 positioned in said second tilt spring position.

12. The apparatus of claim 10, wherein:

said structural actuator includes a first fluid cylinder,

said first fluid cylinder is positionable  
5 between a first rod retracted position and a first rod extended position,

said first fluid cylinder positions said structural spring in said first structural spring position when said first fluid cylinder is positioned  
10 in said first rod retracted position,

said first fluid cylinder positions said structural spring in said second structural spring position when said first fluid cylinder is positioned in said first rod extended position,

15 said tilt actuator includes a second fluid cylinder,

said second fluid cylinder is positionable between a second rod retracted position and a second rod extended position,

20 said second fluid cylinder positions said tilt spring in said first tilt spring position when said second fluid cylinder is positioned in said second rod retracted position, and

said second fluid cylinder positions said  
25 tilt spring in said second tilt spring position when said second fluid cylinder is positioned in said second rod extended position.

13. The apparatus of claim 12, wherein:

30 said first fluid cylinder includes (1) a first rod, (2) a first housing, (3) a first cylinder spring, and (4) a first fluid chamber,

said first cylinder spring urges said first rod into said first housing so as to position said

first fluid cylinder in said first rod retracted position, and

fluid pressure within said first fluid chamber urges said first rod out of said first housing so as to position said first fluid cylinder in said first rod extended position,

said second fluid cylinder includes (1) a second rod, (2) a second housing, (3) a second cylinder spring, and (4) a second fluid chamber,

said second cylinder spring urges said second rod into said second housing so as to position said second fluid cylinder in said second rod retracted position, and

fluid pressure within said second fluid chamber urges said second rod out of said second housing so as to position said second fluid cylinder in said second rod extended position.

14. The apparatus of claim 10, wherein:

said structural actuator includes a structural lever positionable between a first structural lever position and a second structural lever position,

said structural lever positions said structural spring in said first structural spring position when said structural lever is positioned in said first structural lever position,

said structural lever positions said structural spring in said second structural spring position when said structural lever is positioned in said second structural lever position,

said tilt actuator includes a tilt lever positionable between a first tilt lever position and a second tilt lever position,

said tilt lever positions said tilt spring in  
said first tilt spring position when said tilt lever is  
positioned in said first tilt lever position, and

said tilt lever positions said tilt spring in  
5 said second tilt spring position when said tilt lever  
is positioned in said second tilt lever position.

15. The apparatus of claim 14, wherein:

said structural lever has a first cam lobe  
10 secured thereto,

rotation of said structural lever causes said  
first cam lobe to move said structural spring between  
said first structural spring position and said second  
structural spring position,

15 said tilt lever has a second cam lobe secured  
thereto, and

rotation of said tilt lever causes said  
second cam lobe to move said tilt spring between said  
first tilt spring position and said second tilt spring  
20 position.

16. A method for coupling a work implement  
to a stick assembly, comprising the steps of:

positioning an implement pin which is secured  
25 to the work implement into a recess of a hook member  
defined in the stick assembly;

advancing an actuator from a first actuator  
position to a second actuator position; and

moving an over-center spring from a unloaded  
30 position in which the over-center spring allows the  
implement pin to advance into the recess of the hook  
member to a loaded position in which the over-center  
spring biases the pin into the recess of the hook  
member, wherein the moving step occurs in response to  
35 the advancing step.

17. The method of claim 16, wherein:  
the actuator includes a fluid cylinder having  
a housing and a rod,

5 the actuator advancing step includes the step  
of retracting the rod into the housing so as to  
position the over-center spring in the loaded position.

18. The method of claim 17, wherein:  
10 the fluid cylinder further includes a  
cylinder spring, and

the rod retracting step includes the step of  
urging the rod into the housing with the cylinder  
spring.

15

19. The apparatus of claim 16, wherein:  
the actuator includes a lever having a cam  
lobe secured thereto, and

the actuator advancing step includes the step  
20 of rotating the lever so as to cause the cam lobe to  
move the over-center spring into the loaded position.



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Claims searched: 1-19

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Date of search: 12 January 1999

**Patents Act 1977**  
**Search Report under Section 17**

**Databases searched:**

UK Patent Office collections, including GB, EP, WO & US patent specifications, in:

UK Cl (Ed.Q): B8H (HPC).

Int Cl (Ed.6): E02F 3/36.

Other: ONLINE : WPI, EDOC, JAPIO

**Documents considered to be relevant:**

Category	Identity of document and relevant passage	Relevant to claims
X	GB 2,177,674 A (BAMFORD). See Figs 3 & 4 & lines 98 to 109, page 3	1
X	US 5,415,235 (JRB). See Figs	1,16

X	Document indicating lack of novelty or inventive step	A	Document indicating technological background and/or state of the art.
Y	Document indicating lack of inventive step if combined with one or more other documents of same category.	P	Document published on or after the declared priority date but before the filing date of this invention.
&	Member of the same patent family	E	Patent document published on or after, but with priority date earlier than, the filing date of this application.